



# Encoders

optical Encoder, digital outputs, 3 channels, 512 - 16384 lines per revolution, Line Driver

For combination with Brushless DC-Motors

## Series IERF3-16384 L

	IERF3	-512 L	-1024 L	-2048 L	-4096 L	-8192 L	-16384 L	
Lines per revolution	N	512	1 024	2 048	4 096	8 192	16 384	
Frequency range, up to <sup>1)</sup>	f	125	250	500	1 000	2 000	2 000	kHz
Signal output, square wave		2+1 Index and complementary outputs					Channels	
Supply voltage	UDD	4,5 5,5					V	
Current consumption, typical <sup>2)</sup>	<b>I</b> DD	typ. 45, m	nax. 70					mA
Index Pulse width <sup>3)</sup>	Po	90 ± 20				90 ± 30		°e
Phase shift, channel A to B	$\Phi$	90 ± 20				90 ± 30		°e
Inertia of sensor magnet	J	1,33						gcm <sup>2</sup>
Operating temperature range		-40 +10	00					°C
Accuracy, typ.		0,1						°m
Repeatability, typ.		0,007						°m
Hysteresis		< 0,001						°m
Edge spacing, min.		62,5						ns
Mass, typ.		16,8						g

<sup>1)</sup> Velocity (min<sup>-1</sup>) =  $f(Hz) \ge 60/N$ 

<sup>2)</sup>  $U_{DD} = 5$  V: with unloaded outputs

<sup>3)</sup> At 2 500 min<sup>-1</sup>

Note: The output signals are TIA-422 compatible. Examples of Line Driver Receivers: ST26C32AB (STM), AM26C32 (TI).

For combination with Motor		
Dimensional drawing A	<l1 [mm]<="" td=""><td></td></l1>	
2214 BXT H	21,3	
Dimensional drawing B	<l1 [mm]<="" td=""><td></td></l1>	
3216 BXT H	23,3	
Dimensional drawing C	<l1 [mm]<="" td=""><td></td></l1>	
4221 BXT H	28,3	

#### Characteristics

These incremental encoders with 3 output channels, in combination with the FAULHABER Brushless DC-Motors, are used for the indication and control of both shaft velocity and direction of rotation as well as for positioning.

The encoder is integrated in the Brushless DC-Motors BXT H-Series and extends the overall length by only 6,2 mm.

With a reflective code disc two square wave signals with 90° phase shift with up to 16348 lines per revolution and one index impulse per motor revolution are generated.

The optical measurement principle allows high accuracy and repeatability for positioning applications.

The Line Driver version has differential signal outputs (TIA-422). Differential signals reduce ambient interference and are suitable for applications with high ambient interference. The Line Driver amplifies the encoder signal which means that long cables can be used without signal degradation.

Differential signal outputs must be decoded by the appropriate receiver module. In addition, a suitable line termination resistance (120 ohm) is possibly useful.

The supply voltage for the encoder and the output signals are interfaced through a ribbon cable, optional with connector.

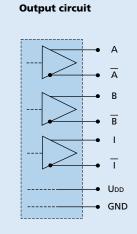
Details for the Brushless DC-Motors and suitable reduction gearheads are on separate catalogue pages.

To view our large range of accessory parts, please refer to the "Accessories" chapter.

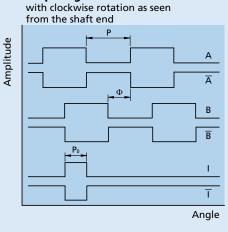


### Circuit diagram / Output signals

**Connector information / Variants** 

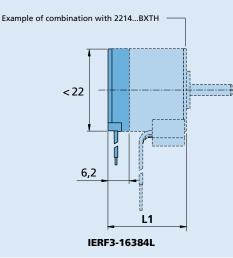


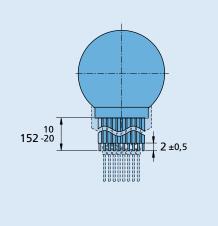
#### Output signals



#### Example product designation: 2214S012BXTH IERF3-4096L **Connection Encoder** Option Description Туре No. Function Connector 3806 for combination with Brushless 1 N.C. DC-Flat Motors series BXT H. 2 Udd Connector variants AWG 28 / PVC ribbon cable with connector EN 60603-13 / DIN-41651. 3 GND 10 9 4 N.C. $\mathsf{Channel}\,\overline{\mathsf{A}}$ 5 6 Channel A for combination with Brushless 7 Channel B Connector 3589 DC-Flat Motors series BXT H. 8 Channel B 2468 1357 Connector variants AWG 28 / PVC ribbon cable 9 Channel I 10 9 with connector EN 60603-13 / DIN-41651. 10 Channel I 10 Inclusive motor connector 3830 Standard cable PVC-ribbon cable, 10-AWG 28, 1,27 mm Higher resolutions with limited speed range are available on request. Resolution Caution: Incorrect lead connection will damage the motor electronics!

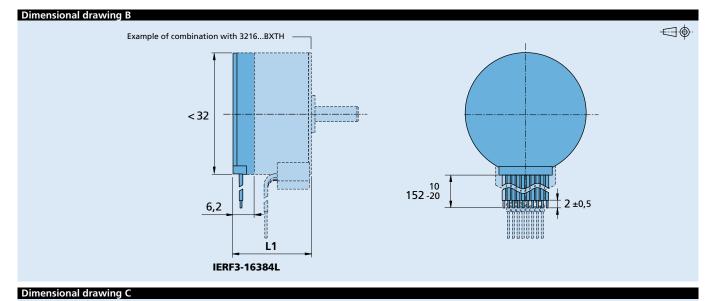
#### **Dimensional drawing A**

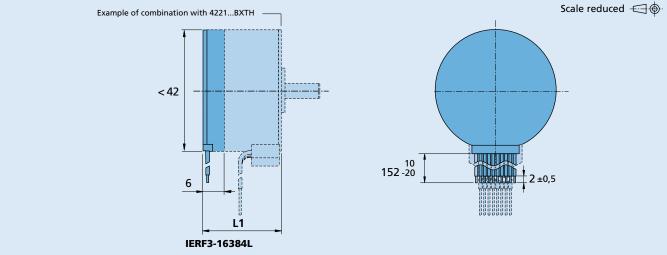




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For notes on technical data and lifetime performance refer to "Technical Information". Edition 2025 Apr. 10